

## MANIPULATOR

## ABSTRACT OF THE DISCLOSURE

A manipulator comprising a foot part and a number of members connected to the foot part and to each other respectively, and at least a gripper part, such that the members and the gripper  
5 constitute, with the foot part, an arm, wherein drive means, in particular motors for moving at least a number of the members and the gripper are provided in the foot part.

09847696.050201  
T02050.9694860